



# ScatSat-1 wind Product User Manual

25 km (OSI-112-a) and 50 km (OSI-112-b) wind products

Version: 1.3

Date: 05/06/2018

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## Document Change record

Document version	Software version	Date	Author	Change description
1.0		15/02/2017	AV	First version
1.1		28/02/2017	AV	Comments from ScatSat PCR included
1.2		11/09/2017	AV	First version for distribution
1.3 draft		16/04/2018	AV	Version for Operational Readiness Review
1.3		05/06/2018	AV	Changes from ORR RIDs

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## 1. Introduction

### 1.1. Overview

The OSCAT scatterometer instrument is mounted on the ScatSat-1 satellite which was launched on September 26<sup>th</sup>, 2016 by the Indian Space Research Organisation (ISRO). The Ku-band OSCAT instrument has some enhanced features compared to OSCAT on Oceansat-2 which was launched in 2009. The level 1b files from ISRO are processed by KNMI into 25 km and 50 km level 2 wind products.

The EUMETSAT Ocean and Sea Ice Satellite Application Facility (OSI SAF) produces a range of air-sea interface products, namely: wind, sea ice characteristics, Sea Surface Temperatures (SST) and radiative fluxes, Surface Solar Irradiance (SSI) and Downward Long wave Irradiance (DLI). The Product Requirements Document [1] provides an overview of the committed products and their characteristics in the current OSI SAF project phase, the Service Specification Document [2] provides specifications and detailed information on the services committed towards the users by the OSI SAF in a given stage of the project.

KNMI is involved in the OSI SAF as the centre where the level 1 to level 2 scatterometer wind processing is carried out. This document is the Product User Manual to the ScatSat-1 wind product. More general information on the OSI SAF project is available on the OSI SAF web site: <http://osi-saf.eumetsat.int>. The user is strongly encouraged to register on this web site in order to receive the service messages and the latest information about the OSI SAF products. More information about this product can also be found on <http://www.knmi.nl/scatterometer/>.

The scatterometer is an instrument that provides information on the wind field near the ocean surface, and scatterometry is the knowledge of extracting this information from the instrument's output. Space-based scatterometry has become of great benefit to meteorology and climate in the past years. This is extensively described in the Algorithm Theoretical Baseline Document, see [3].

KNMI has a long experience in scatterometer processing and is developing generic software for this purpose. Processing systems have been developed for the ERS, NSCAT, SeaWinds, ASCAT, OSCAT and RapidScat scatterometers. Scatterometer processing software is distributed through the EUMETSAT Numerical Weather Prediction Satellite Application Facility (NWP SAF), whereas wind processing is performed operationally in the Ocean and Sea Ice SAF (OSI SAF).

The OSI SAF products are delivered on request through the KNMI FTP server and through EUMETCast. See also <http://www.knmi.nl/scatterometer/> for real-time graphical examples of the products and up-to-date information and documentation.

This user manual outlines user information for the OSI SAF ScatSat-1 winds on 25 km (OSI-112-a) and 50 km (OSI-112-b) grid spacing. Section 2 presents a brief description of the OSCAT instrument, and section 3 gives an overview of the data processing configuration. Detailed information on the file content and format is given in section 4. The product quality is elaborated in section 5 and in the validation report to these products [5].

### 1.2. Acknowledgement

ISRO kindly provides the near-real time OSCAT level 1b data which are used as input for the OSI SAF wind products.

### 1.3. Disclaimer

All intellectual property rights of the OSI SAF products belong to EUMETSAT. The use of these products is granted to every interested user, free of charge. If you wish to use these products, EUMETSAT's copyright credit must be shown by displaying the words "copyright (year) EUMETSAT" on each of the products used.

The OSI SAF is much interested in receiving your feedback, would appreciate your acknowledgment in using and publishing about the data, and we like to receive a copy of any publication about the application of the data. Your feedback, e.g., directed to [scat@knmi.nl](mailto:scat@knmi.nl), helps us in maintaining the resources for the OSI SAF wind services.

### 1.4. Useful links

KNMI scatterometer web site: <http://www.knmi.nl/scatterometer/>

Information on OSI SAF activities at KNMI: <http://www.knmi.nl/scatterometer/osisaf/>

OSI SAF wind product documentation on <http://osi-saf.eumetsat.int>

NWP SAF website: <http://nwp-saf.eumetsat.int>

ScatSat visual products:

[http://www.knmi.nl/scatterometer/scasa\\_25\\_prod/](http://www.knmi.nl/scatterometer/scasa_25_prod/) (25 km)

[http://www.knmi.nl/scatterometer/scasa\\_50\\_prod/](http://www.knmi.nl/scatterometer/scasa_50_prod/) (50 km)

EUMETSAT Data Centre:

<http://www.eumetsat.int/website/home/Data/DataDelivery/EUMETSATDataCentre/index.html>

ScatSat-1 information on ISRO web site: <http://isro.gov.in/Spacecraft/scatsat-1>

### 1.5. Helpdesk and data availability

For a swift response management procedure, user requests on the OSI SAF data products should be issued at the Ocean and Sea Ice SAF website.

The BUFR products are not yet disseminated on EUMETCast. This will be implemented after the product gets the operational status.

The BUFR and NetCDF products are also made available on a password-protected ftp site (data from the last three days only). The access details are provided to new users by email request. Please send your requests to [scat@knmi.nl](mailto:scat@knmi.nl).

The products can be distinguished w.r.t. product swath grid spacing by their file names, see section 4.2.

A BUFR reader is available at [www.knmi.nl/scatterometer/bufr\\_reader/](http://www.knmi.nl/scatterometer/bufr_reader/).

The products will be available from the EUMETSAT Data Centre in the future. KNMI also keeps an off-line archive of the products. You can send a request to [scat@knmi.nl](mailto:scat@knmi.nl).

### 1.6. Limitations and remaining issues

- 1) The timeliness of the products is not always optimal, delays of more than 12 hours occur from time to time. ISRO is working on this problem.

- 2) Product quality improvements are obtained by regular activities in the OSI SAF; these are now focussed on the following remaining minor anomalies: 1) SST dependency, 2) wind direction modulation and 3) high ScatSat-1 backscatter and winds, and will be followed by announcing minor product updates in due time.

## 1.7. History of product changes

Here is an historical overview of the changes in the ScatSat-1 wind products:

- 25-Jan-2017 First internal development version of OSCAT wind product. PenWP version is 2\_0\_01.
- 12-Sep-2017 First version for external distribution based on ISRO Level 1b version 1.1.2 data.
- 27-Nov-2017 Some small bug fixes and improvements. PenWP version is 2\_1\_05.
- 20-Mar-2018 ISRO has moved to data processing software version 1.1.3.

## 2. The OSCAT scatterometer

ScatSat-1 is a continuity mission for the Oceansat-2 scatterometer, which provided useful ocean vector wind observations used in, among others, oceanography, Numerical Weather Prediction (NWP) and nowcasting. ScatSat-1 carries the Ku-band OSCAT scatterometer which is similar to the one flown on-board Oceansat-2, with some enhanced features based on lessons learnt. The spacecraft is in a sun-synchronous orbit of 720 km altitude with an inclination of 98.1°. ScatSat-1 was launched on September 26<sup>th</sup>, 2016. The local time of Equator crossing was 9:20. Since then, the local time of Equator crossing is slowly drifting towards a time which will be approximately 8:00 at the end. In May 2018, the local time of Equator crossing was approximately 8:45. This is still very close to that of Metop-A and Metop-B (9:30) and as such it allows cross-calibration with ASCAT. For detailed information on the OSCAT instrument and data we refer to [6] and [7]. A brief description is given below.

The OSCAT instrument is a conically scanning pencil-beam scatterometer, as depicted in figure 1. It uses a 1-meter dish antenna rotating at 20 rpm with two “spot” beams of about 25 km × 55 km size on the ground, a horizontal polarisation beam (HH) and a vertical polarisation beam (VV) at incidence angles of 49° and 58° respectively. The beams sweep the surface in a circular pattern as depicted in Figure 1. Note that the egg-shaped beam footprints are divided into slices by applying a modulated chirp signal. Due to the conical scanning, a Wind Vector Cell (WVC) is generally viewed when looking forward (fore) and a second time when looking aft. As such, up to four measurement classes (called “beam” here) emerge: HH fore, HH aft, VV fore, and VV aft, in each WVC. The 1800-km-wide swath covers 90% of the ocean surface in 24 hours which is substantially higher than side-looking scatterometers like ERS, NSCAT and ASCAT.

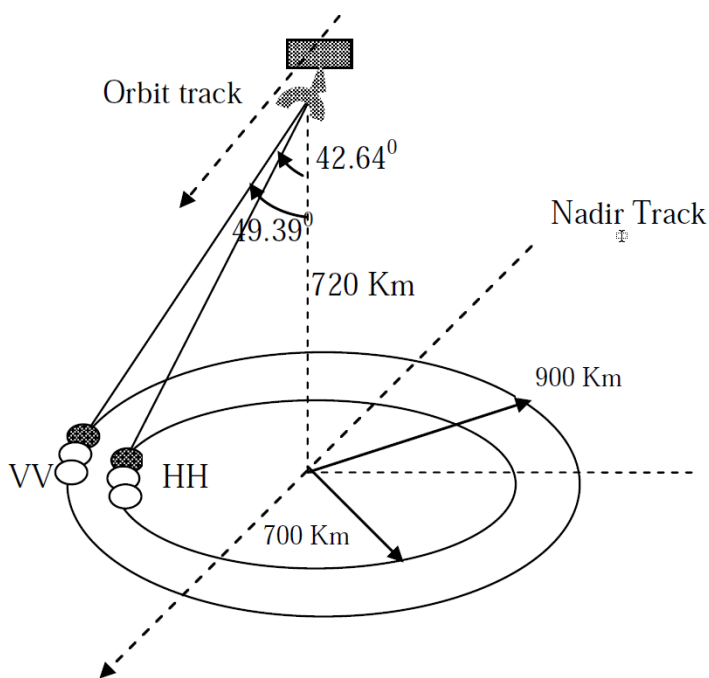


Figure 1: OSCAT pencil beam geometry (source: [6]).

The wind retrieval from OSCAT data is not trivial. In contrast with side-looking scatterometers like ASCAT, the number of measurements and the beam azimuth angles vary with the sub-satellite cross-track location. The wind retrieval skill will therefore depend on the position in the swath. A detailed discussion is provided in [3]. Here we only summarise some issues specific to OSCAT.

In the outer swath (where only VV beam data are available), the individual backscatter measurements ('slices') contributing to the VV fore or aft beam in a specific WVC are re-distributed to form four independent backscatter observations. Slices are accumulated and averaged based on their azimuth angles. The outer swath winds have slightly reduced quality control skill, but they are still very well usable. These winds are flagged in the product and can be filtered out easily if requested, see section 4.2.

The OSCAT scatterometer operates at a Ku-band radar frequency (13.5 GHz corresponding to ~2 cm wavelength). The atmosphere is not transparent at these wavelengths and in particular rain is detrimental for wind computation. In fact, moderate and heavy rain cause bogus wind retrievals of 15-20 m/s wind speed which need to be eliminated by a Quality Control (QC) step. Wind-rain discrimination is easiest to manage in the sweet swath, but still performs acceptably in nadir and outer swath.

The processing algorithms for the OSCAT wind processing are heavily based on the algorithms as developed for SeaWinds, RapidScat and OSCAT on Oceansat-2 [3]. When calibrated geophysical backscatter measurements are available, the wind processing of the different Ku-band pencil-beam scatterometers is very similar. The wind processing software which is used, the Pencil beam Wind Processor (PenWP), is the successor of the SeaWinds Data Processor (SDP) and the OSCAT Wind Data Processor (OWDP). PenWP is capable to process data from SeaWinds, OSCAT, RapidScat and HY-2A scatterometers and replaces all former pencil beam Ku-band wind processing software packages in the NWP SAF.

Differences between the various rotating pencil beam scatterometers are to a great extent on a technical (data formats and handling) level. Moreover, due to different orbits and antenna geometries, incidence angles differ. PenWP utilises the NSCAT-4 Geophysical Model Function (GMF) [3], which is available for all prevailing incidence angles. In order to handle instrument differences well, particularly noise characteristics, some parts of the processing were re-tuned for ScatSat-1, mainly the normalisation of the Maximum Likelihood Estimator (MLE) and the tuning of the Quality Control [4].



### 3. Processing scheme

KNMI has a processing chain running in near-real time with ScatSat-1 data, including wind maps displayed on the OSI SAF web site. The processing software is developed in the OSI SAF and runs in the KNMI operational environment. The processing includes monitoring and archiving functionalities. General information about the scatterometer wind processing algorithms can be found in the Algorithm Theoretical Basis Document (ATBD) [3]. The products are distributed through several means (e.g., FTP, EUMETCast, see section 1.5) and the software packages are available on the NWP SAF software portal.

#### 3.1. Backscatter slice averaging

The level 1b backscatter data from ISRO are organised in slices [6]. The slices are beam-wise accumulated to a WVC level before wind inversion is done. The slice weights are proportional to the estimated transmitted power contained in a slice, i.e., inversely proportional to the  $K_p$  value. The Sigma0 Quality Flag present in the level 1b data is evaluated and slice data with one of the following flags set are skipped:

- Bit 4: Sigma0 is poor
- Bit 5:  $K_p$  (noise value) is poor
- Bit 6: Invalid footprint
- Bit 7: Footprint contains saturated slice

#### 3.2. Backscatter calibration

No absolute instrumental instrument calibration exists for Ku-band pencil-beam scatterometers. Ku-band pencil-beam backscatter distributions should however be matched to achieve wind intercalibration of all space-borne scatterometer instruments. We thus developed methods that calibrate the winds of each scatterometer effectively to the mean winds at collocated moored buoys. No significant signs of azimuth (or WVC) dependent instrument biases have been found for ScatSat-1. Also the beam incidence angles are constant and hence we have chosen to apply backscatter corrections that are only dependent on the beam polarisation. The goal of applying backscatter corrections was to minimise wind speed biases between scatterometer winds on the one hand and buoy and NWP winds on the other hand. With this in mind, the calibration correction for VV has been obtained by looking at the outer swath data (where no HH data are available) and choosing a calibration amount that yields minimum wind speed biases. Subsequently, the swath part containing both HH and VV was considered, the VV correction was applied and a HH correction was obtained that again yields minimum biases. In this simple way, within a few iterations the two calibration coefficients could be obtained:

- For HH, 1.08 dB has been added in the 25 km products and 0.98 dB in the 50 km products
- For VV, 0.35 dB has been added in the 25 km products and 0.27 dB in the 50 km products

The common part of the correction is thought to be a resetting of the instrument's gain towards the setting used for other scatterometers (intercalibration), while the incremental enhancement for the 25 km products is a wind speed retrieval correction depending on input noise.

In the OSI SAF wind processing, an additional instrument gain correction above backscatter values of -19 dB has been implemented of about 0.1 dB decrease per additional dB. This correction makes the

climatology of retrieved wind speeds above 15 m/s clearly more similar to other pencil-beam scatterometers, while its origin has not been confirmed by ISRO. Note that the calibrated backscatter values are only available within the wind processing software; the  $\sigma^0$  data in the BUFR wind product are uncorrected values.

### 3.3. NWP collocation

KNMI receives NWP model data from ECMWF twice a day through the Regional Meteorological Data Communication Network (RMDCN).

NWP model sea surface temperature (SST) data are used to support the Bayesian sea ice discrimination [3]. The SST values of the four surrounding model grid points around the WVC location are bi-linearly interpolated. Note that the ECMWF model data do not contain SST values over land; if one or more of the four surrounding grid points has missing SST data, the SST value of the grid point closest to the WVC is taken. WVCs with a sea surface temperature above 5 °C are assumed to be always open water. The Bayesian ice screening procedure may sometimes assign rainy WVCs erroneous as ice; using the extra SST criterion, WVCs in areas warmer than 5 °C will never be labelled as ice. Due to its rather 'warm' threshold value, the NWP-based SST ice screening will only be active in regions far away from the ice extents.

Land presence within each WVC is determined by using the land-sea mask available from the model data. The weighted mean value of the land fractions of all model grid points within 50 km (60 km in the 50 km products) of the WVC centre is calculated. The weight of each grid point scales with  $1/r^2$ , where  $r$  is the distance between the WVC centre and the model grid point. If this mean land fraction value exceeds a threshold of 0.02, no wind retrieval is performed.

NWP forecast wind data are necessary in the ambiguity removal step of the processing. Wind forecasts are available twice a day (00 and 12 GMT analysis time) with forecast time steps of +3h, +4h, +5h, ..., +30h. The model wind data are quadratically interpolated with respect to time and bi-linearly interpolated with respect to location and put into the level 2 information part of each WVC (see section 4.2). The ECMWF winds stored in the wind products are stress-equivalent winds [8] which have been computed from the equivalent neutral model winds.

### 3.4. Quality control and monitoring

In each WVC, the  $\sigma^0$  data is checked for quality and completeness and the inversion residual [3], called MLE, is checked. Degraded WVCs are flagged; see section 4.2 for more details.

An information file is made for each product. The content of the file is identical whatever the product and results from a compilation of all the global information concerning this product. From these files, various graphs have been produced to visually display the confidence levels of the products and their evolution with time. Any deviations from nominal behaviour would be immediately visible as steps in these graphs. Data and overall product quality is also available to the users within the products; see section 4 for a description of quality flags.

## 4. Data description

### 4.1. Wind product characteristics

#### 4.1.1. Physical definition

Horizontal stress-equivalent wind vector at 10 m height, obtained using the NSCAT-4 GMF, see [3] [8].

#### 4.1.2. Units and range

Wind speed is measured in m/s. The wind speed range is from 0-50 m/s, but wind speeds exceeding 25 m/s are generally less reliable [3]. In the BUFR products, the wind direction is in *meteorological* (World Meteorological Organisation, WMO) convention relative to North: 0 degrees corresponds to a wind flowing to the *South* with a clockwise increment. In the NetCDF products, the wind direction is in *oceanographic* convention: 0 degrees corresponds to a wind flowing to the *North* with a clockwise increment.

#### 4.1.3. Input satellite data

The ScatSat-1 level 1b input data [7] are kindly provided by ISRO. The products contain geo-located backscatter measurements on a satellite swath WVC grid of 25 km size or 50 km.

#### 4.1.4. Geographical definition

The ScatSat-1 satellite flies in a near-polar sun synchronous orbit at 98 degrees inclination at approximately 720 km orbit height. The swath width is 1800 km and the swath is composed of 76 25 km size WVCs or 38 50 km size WVCs. Products are organised in files containing one half orbit; either from the North Pole to the South Pole or from the South Pole to the North Pole.

#### 4.1.5. Output product

The input product in HDF format is processed into a BUFR output product including a unique wind solution (chosen), its corresponding ambiguous wind solutions and quality information (distance to cone, quality flag). The products are also available in NetCDF format; see section 9 for more details.

#### 4.1.6. Expected accuracy

The expected accuracy is defined as the expected bias and standard deviation of the primary calculations. The accuracy is validated against in situ wind measurements from buoys, and against NWP data. Even better, the errors of all NWP model winds, in situ data, and scatterometer winds are computed in a triple collocation exercise [10]. The performance is pretty constant over the globe and depends mainly on the sub footprint wind variability. According to the OSI SAF product requirements [2] the accuracy should be better than 2 m/s in wind component standard deviation with a bias of less than 0.5 m/s in wind speed. More validation information is available in [5], showing that the actual product accuracy well exceeds the requirements.

### 4.2. File formats

Wind products are in BUFR Edition 4 or in NetCDF format. A complete description of BUFR can be found in WMO publication No 306, Manual on Codes.

The OSI SAF wind product is stored in exactly the same BUFR format as described in the SeaWinds BUFR manual from NOAA [9], a list of descriptors (fields) contained in each WVC is provided in section 8. Data are organised in files containing approximately one half orbit (50 minutes) of data.

#### 4.2.1. File name conventions

The file name convention for the level 2 BUFR product on the KNMI FTP server is

oscat\_YYYYMMDD\_HHMMSS\_scasa1\_ORBIT\_T\_SMPL\_CONT\_I2.bufr

- YYYYMMDD denotes the acquisition date (year, month and day) of the first data in the file
- HHMMSS denotes the acquisition time (hour, minute and second) of the first data in the file
- ORBIT is the orbit number of the first data in the file (00000-99999)
- T is the processing type (o for operational, t for test)
- SMPL is the WVC sampling (cell spacing): 250 for the 25 km and 500 for the 50 km product
- CONT refers to the product contents: always ovw for a product containing Ocean Vector Winds

Examples of file names are

oscat\_20180403\_215814\_scasa1\_08043\_o\_250\_owv\_I2.bufr for a 25 km product

oscat\_20180403\_215814\_scasa1\_08043\_o\_500\_owv\_I2.bufr for a 50 km product

The file names on EUMETCast are different from those on the FTP server and according to the WMO conventions

W\_NL-KNMI-DeBilt,SURFACE+SATELLITE,SCATSAT1+OSCAT\_C\_EHDB\_YYYYMMDDHHMMSS\_ORBIT\_T\_SMPL\_CONT\_I2.bin

The meaning of the acronyms in the file names is the same as for the files on FTP. Example file names are

W\_NL-KNMI-DeBilt,SURFACE+SATELLITE,SCATSAT1+OSCAT\_C\_EHDB\_20180403215814\_08043\_o\_250\_owv\_I2.bin

W\_NL-KNMI-DeBilt,SURFACE+SATELLITE,SCATSAT1+OSCAT\_C\_EHDB\_20180403215814\_08043\_o\_500\_owv\_I2.bin

#### 4.2.2. File contents

In each node or wind vector cell (WVC) 118 data descriptors are defined. In addition some extra information/alterations have been put in place:

- In the BUFR header the value for “generating centre” is set to 99, representing KNMI.
- The products contain up to four ambiguous wind solutions, with an index to the selected wind solution. After the wind inversion step, we initially store the up to four solutions corresponding to the inversion residual (Maximum Likelihood Estimator, MLE) relative minima. However, subsequently the wind speed and wind direction of the after 2DVAR-selected Multiple Solution Scheme (MSS) wind solution is put at the index of the selected wind solution. This index is set to the initial wind vector solution which is closest to the MSS wind vector selection obtained after 2DVAR. Thus, the former wind vector is not provided in the product, but rather the MSS selected wind vector. The ‘Formal Uncertainty in Wind Direction’ does not contain the uncertainty, but the normalised inversion residual (referred to as  $R_n$  in [11]).
- The ‘SeaWinds Probability of Rain’ and ‘SeaWinds NOF Rain Index’ BUFR fields are not used and contain missing data values.

- The Wind Vector Cell Quality Flag (table 021109) is redefined and now has the following definitions:

Description	BUFR bit	Fortran bit
Reserved	1	16
Not enough good sigma-0 available for wind retrieval	2	15
Not used	3	14
VV polarised data in more than two beams	4	13
Product monitoring not used	5	12
Product monitoring flag	6	11
KNMI Quality Control (including rain) data rejection	7	10
Variational QC data rejection	8	9
Land presence	9	8
Ice presence	10	7
Not used	11	6
Reported wind speed is greater than 30 m/s	12	5
Reported wind speed is less than or equal to 3 m/s	13	4
Not used	14	3
Rain flag algorithm detects rain	15	2
Data from at least one of the four possible beam/view combinations are not available	16	1
Missing value	All 17 set	All 17 set

In Fortran, if the Wind Vector Cell Quality Flag is stored in an integer **I** then use **BTEST(I,NDW-NB)** to test BUFR bit **NB**, where **NDW=17** is the width in bits of the data element in BUFR. The **BTEST** function is equivalent to **(I/2<sup>NB</sup>) modulo 2** where **NB** is the Fortran bit number.

The flag indicating that more than two beams contain VV polarised data, BUFR bit 3, is active in the outer part of the swath (WVCs 1-8 and 69-76 at 25 km, WVCs 1-4 and 35-38 at 50 km). It indicates that outer beam data is used to obtain four independent  $\sigma^0$  values, contrary to the middle part of the swath where two beams contain VV (outer beam) data and two beams contain HH (inner beam) data. In the outer parts of the swath, the VV backscatter data present in the level 1b product are distributed to two WVC beams based on their azimuth angle such that maximum azimuth dispersion is obtained. This generally results in slightly less optimal wind retrieval; users assimilating the data into NWP models may consider to reject WVCs for which this flag is set.

If the 'product monitoring not used' bit, Fortran bit 12, is set to zero, the product is monitored. If the product is monitored and the 'product monitoring flag' bit, Fortran bit 11, is set to zero, the product is valid; otherwise it is rejected by the product monitoring [3]. This is based on a statistical check of the number of WVC QC rejections, the wind speed bias with respect to the NWP background, and the wind vector RMS difference with respect to the NWP background. The product monitoring bits have the same value for all WVCs in one BUFR output file.

If the KNMI QC flag, Fortran bit 10, is set in a WVC, then the backscatter information is not useable for various geophysical reasons like rain, confused sea-state etc, resulting in a too large inversion residual. WVCs in which the KNMI QC flag is set, are not used in the calculation of the analysis field in the ambiguity removal step. However, after the ambiguity removal the wind solution closest to the analysis field is chosen (if wind solutions are present in the WVC). This means that such a WVC may contain a selected wind solution, but it is suspect.

The land presence flag, Fortran bit 8, is set if a land fraction (see section 3.3) larger than zero is calculated for the WVC. As long as the land fraction is below the limit value, a reliable wind solution may however still be present so there is normally no reason to reject WVCs with the land flag set.

The Bayesian ice screening algorithm as implemented in PenWP is used in the processing. The ice presence flag, Fortran bit 7, is set if the Bayesian sea ice screening algorithm calculates ice for the WVC [3]. Note that the products contain wind solutions also over sea ice regions. These bogus winds are flagged both by the KNMI quality control flag and by the ice flag. Hence it is important to reject any winds with the KNMI quality control flag set when ingesting the products. Note that WVCs that are rejected due to a large inversion residual (e.g., in case of excessive local wind variability), only have the KNMI quality control flag set. On the other hand, WVCs that are rejected due to sea ice, have both the KNMI quality control flag and the ice flag set.

If the variational QC flag, Fortran bit 9, is set, the wind vector in the WVC is rejected during ambiguity removal due to spatial inconsistency. A wind solution is present, but it may be suspect.

It is recommended not to automatically use WVCs with the product monitoring flag, the KNMI quality control flag or the variational quality control flag set. See [3] for more information on product reliability. However, in nowcasting applications, the flagged data may be visually inspected in their meteorological context and hence be rather useful for trained meteorologists.



## 5. Data quality

As stated in the OSISAF product requirements [2], the accuracy should be better than 2 m/s in wind component standard deviation with a bias of less than 0.5 m/s in wind speed.

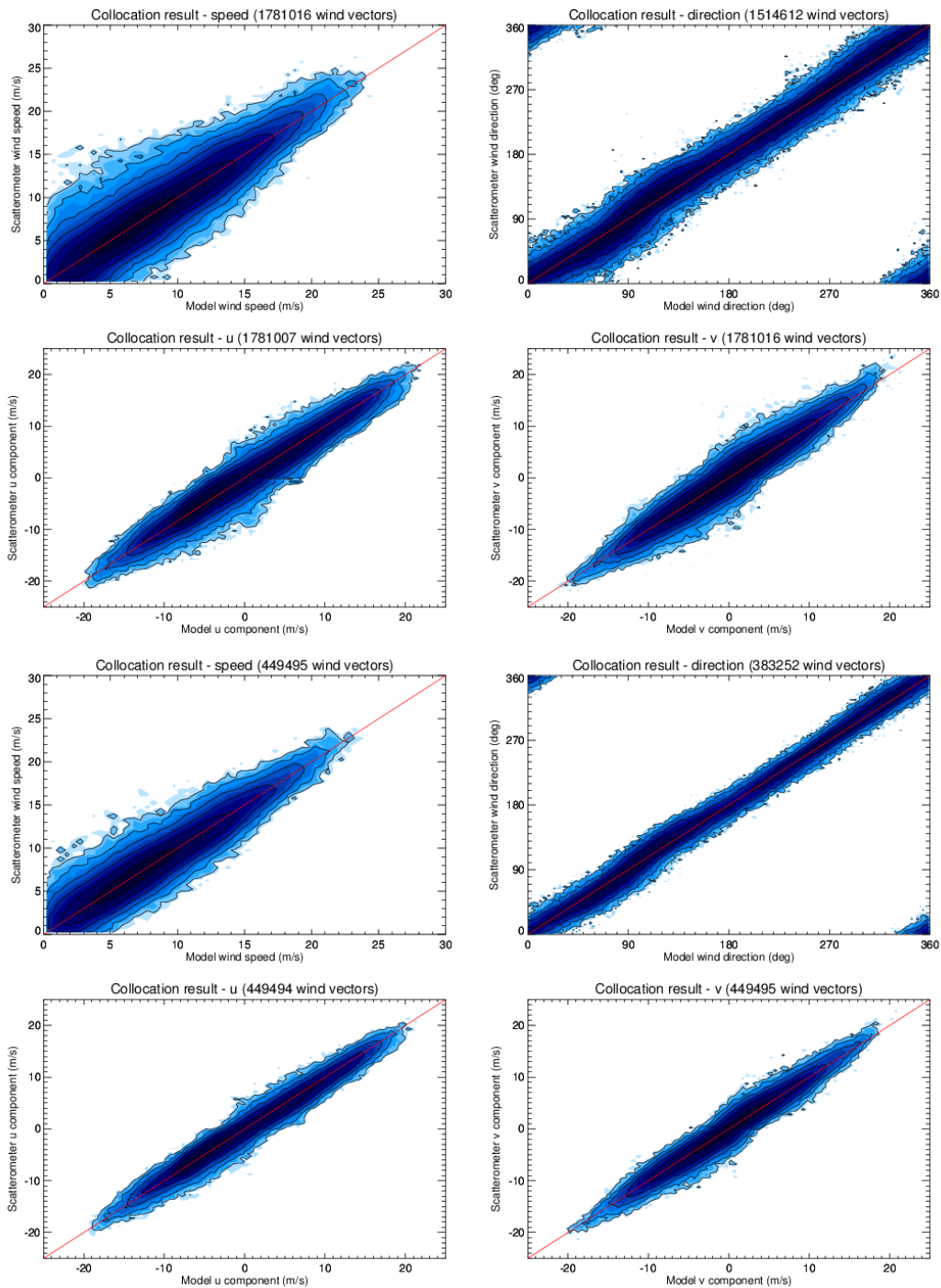


Figure 2: Two-dimensional scatter density plots of wind speed, direction (w.r.t. wind coming from the North), u and v components of 25 km (top) and 50 km (bottom) ScatSat-1 wind product versus the ECMWF model forecast winds from 4-5 April 2018.

Figure 2 shows two-dimensional scatter density plots of the retrieved winds versus ECMWF 10 m stress-equivalent background winds for the 25 km and 50 km wind products, after rejection of Quality Controlled (KNMI QC flagged) wind vectors. The top left plot in each panel corresponds to wind speed (bins of 0.5 m/s) and the top right plot to wind direction (bins of 2.5°). The latter are computed for only ECMWF winds larger than 4 m/s. The bottom plots show the  $u$  and  $v$  wind component statistics (bins of 0.5 m/s). The contour lines are in logarithmic scale.

From these results, it is clear that the spread in the distributions is small. The wind speed bias is -0.01 m/s for 25 km and 0.00 m/s for 50 km, close to zero. The wind component standard deviations of the differences are around 1.3 m/s for the 25 km product and around 1.1 m/s for the 50 km product.

The overall product error standard deviations in the zonal ( $u$ ) and meridional ( $v$ ) wind components at the product resolution is evaluated by triple collocation and given in the following table [5]:

	Scatterometer		Buoys		ECMWF	
	$\epsilon_u$ (m/s)	$\epsilon_v$ (m/s)	$\epsilon_u$ (m/s)	$\epsilon_v$ (m/s)	$\epsilon_u$ (m/s)	$\epsilon_v$ (m/s)
<b>25 km ScatSat-1</b>	<b>0.77</b>	<b>0.60</b>	<b>1.37</b>	<b>1.40</b>	<b>1.10</b>	<b>1.13</b>
<b>50 km ScatSat-1</b>	<b>0.60</b>	<b>0.44</b>	<b>1.45</b>	<b>1.50</b>	<b>0.99</b>	<b>1.00</b>

The 25 km product is less accurate, but provides a better representation of the buoy winds than the 50 km product. On the other hand, the latter product is more representative of global NWP models. Much more validation information can be found in [5].



## 6. References

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## 7. Abbreviations and acronyms

2DVAR	Two-dimensional Variational Ambiguity Removal
ATBD	Algorithm Theoretical Basis Document
AR	Ambiguity Removal
ASCAT	Advanced Scatterometer
BUFR	Binary Universal Format Representation
DLI	Downward Long wave Irradiance
ECMWF	European Centre for Medium-Range Weather Forecasts
ERS	European Remote-Sensing Satellite
EUMETCast	EUMETSAT's Digital Video Broadcast Data Distribution System
EUMETSAT	European Organisation for the Exploitation of Meteorological Satellites
GMF	Geophysical Model Function
HDF	Hierarchical Data Format
HH	Horizontal polarisation of sending and receiving radar antennas
ISRO	Indian Space Research Organisation
KNMI	Royal Netherlands Meteorological Institute
MLE	Maximum Likelihood Estimator
MSS	Multiple Solution Scheme
NASA	National Aeronautics and Space Administration (USA)
NetCDF	Network Common Data Form
NOAA	National Oceanic and Atmospheric Administration (USA)
NSCAT	NASA Scatterometer
NWP	Numerical Weather Prediction
OSCAT	Scatterometer on-board the Oceansat-2 and ScatSat-1 satellites (India)
OSI SAF	Ocean and Sea Ice SAF
OWDP	OSCAT Wind Data Processor
PenWP	Pencil beam Wind Processor
RMDCN	Regional Meteorological Data Communication Network
QC	Quality Control
QuikSCAT	US Quick Scatterometer mission carrying the SeaWinds scatterometer
SAF	Satellite Application Facility
SDP	SeaWinds Data Processor
SeaWinds	Scatterometer on-board QuikSCAT platform (USA)

SSI	Surface Solar Irradiance
SST	Sea Surface Temperature
$u$	West-to-east (zonal) wind component
$v$	South-to-north (meridional) wind component
VV	Vertical polarisation of sending and receiving radar antennas
WMO	World Meteorological Organisation
WVC	Wind Vector Cell

## 8. Appendix A: BUFR data descriptors

Number	Descriptor	Parameter	Unit
001	(01007)	Satellite Identifier	Code Table
002	(01012)	Direction of Flight	Degree True
003	(02048)	Satellite Instrument Identifier	Code Table
004	(21119)	Wind Scatterometer GMF	Code Table
005	(25060)	Software Identification	Numeric
006	(02026)	Cross Track Resolution	m
007	(02027)	Along Track Resolution	m
008	(05040)	Orbit Number	Numeric
009	(04001)	Year	Year
010	(04002)	Month	Month
011	(04003)	Day	Day
012	(04004)	Hour	Hour
013	(04005)	Minute	Minute
014	(04006)	Second	Second
015	(05002)	Latitude (Coarse Accuracy)	Degree
016	(06002)	Longitude (Coarse Accuracy)	Degree
017	(08025)	Time Difference Qualifier	Code Table
018	(04001)	Time to Edge	Second
019	(05034)	Along Track Row Number	Numeric
020	(06034)	Cross Track Cell Number	Numeric
021	(21109)	Seawinds Wind Vector Cell Quality Flag	Flag Table
022	(11081)	Model Wind Direction At 10 M	Degree True
023	(11082)	Model Wind Speed At 10 M	m/s
024	(21101)	Number of Vector Ambiguities	Numeric
025	(21102)	Index of Selected Wind Vector	Numeric
026	(21103)	Total Number of Sigma0 Measurements	Numeric
027	(21120)	Seawinds Probability of Rain	Numeric
028	(21121)	Seawinds NOF Rain Index	Numeric
029	(13055)	Intensity Of Precipitation	kg/m**2/sec
030	(21122)	Attenuation Correction On Sigma-0 (from Tb)	dB
031	(11012)	Wind Speed At 10 M	m/s
032	(11052)	Formal Uncertainty In Wind Speed	m/s
033	(11011)	Wind Direction At 10 M	Degree True
034	(11053)	Formal Uncertainty In Wind Direction	Degree True
035	(21104)	Likelihood Computed for Wind Solution	Numeric
036	(11012)	Wind Speed At 10 M	m/s
037	(11052)	Formal Uncertainty In Wind Speed	m/s
038	(11011)	Wind Direction At 10 M	Degree True
039	(11053)	Formal Uncertainty In Wind Direction	Degree True
040	(21104)	Likelihood Computed for Wind Solution	Numeric
041	(11012)	Wind Speed At 10 M	m/s
042	(11052)	Formal Uncertainty In Wind Speed	m/s
043	(11011)	Wind Direction At 10 M	Degree True
044	(11053)	Formal Uncertainty In Wind Direction	Degree True
045	(21104)	Likelihood Computed for Wind Solution	Numeric
046	(11012)	Wind Speed At 10 M	m/s
047	(11052)	Formal Uncertainty In Wind Speed	m/s
048	(11011)	Wind Direction At 10 M	Degree True

Number	Descriptor	Parameter	Unit
049	(11053)	Formal Uncertainty In Wind Direction	Degree True
050	(21104)	Likelihood Computed for Wind Solution	Numeric
051	(02104)	Antenna Polarisation	Code Table
052	(08022)	Total Number w.r.t. accumulation or average	Numeric
053	(12063)	Brightness Temperature	K
054	(12065)	Standard Deviation Brightness Temperature	K
055	(02104)	Antenna Polarisation	Code Table
056	(08022)	Total Number w.r.t. accumulation or average	Numeric
057	(12063)	Brightness Temperature	K
058	(12065)	Standard Deviation Brightness Temperature	K
059	(21110)	Number of Inner-Beam Sigma0 (fwd of sat.)	Numeric
060	(05002)	Latitude (Coarse Accuracy)	Degree
061	(06002)	Longitude (Coarse Accuracy)	Degree
062	(21118)	Attenuation Correction On Sigma-0	dB
063	(02112)	Radar Look (Azimuth) Angle	Degree
064	(02111)	Radar Incidence Angle	Degree
065	(02104)	Antenna Polarisation	Code Table
066	(21105)	Normalized Radar Cross Section	dB
067	(21106)	Kp Variance Coefficient (Alpha)	Numeric
068	(21107)	Kp Variance Coefficient (Beta)	Numeric
069	(21114)	Kp Variance Coefficient (Gamma)	dB
070	(21115)	Seawinds Sigma-0 Quality Flag	Flag Table
071	(21116)	Seawinds Sigma-0 Mode Flag	Flag Table
072	(08018)	Seawinds Land/Ice Surface Flag	Flag Table
073	(21117)	Sigma-0 Variance Quality Control	Numeric
074	(21111)	Number of Outer-Beam Sigma0 (fwd of sat.)	Numeric
075	(05002)	Latitude (Coarse Accuracy)	Degree
076	(06002)	Longitude (Coarse Accuracy)	Degree
077	(21118)	Attenuation Correction On Sigma-0	dB
078	(02112)	Radar Look (Azimuth) Angle	Degree
079	(02111)	Radar Incidence Angle	Degree
080	(02104)	Antenna Polarisation	Code Table
081	(21105)	Normalized Radar Cross Section	dB
082	(21106)	Kp Variance Coefficient (Alpha)	Numeric
083	(21107)	Kp Variance Coefficient (Beta)	Numeric
084	(21114)	Kp Variance Coefficient (Gamma)	dB
085	(21115)	Seawinds Sigma-0 Quality Flag	Flag Table
086	(21116)	Seawinds Sigma-0 Mode Flag	Flag Table
087	(08018)	Seawinds Land/Ice Surface Flag	Flag Table
088	(21117)	Sigma-0 Variance Quality Control	Numeric
089	(21112)	Number of Inner-Beam Sigma0 (aft of sat.)	Numeric
090	(05002)	Latitude (Coarse Accuracy)	Degree
091	(06002)	Longitude (Coarse Accuracy)	Degree
092	(21118)	Attenuation Correction On Sigma-0	dB
093	(02112)	Radar Look (Azimuth) Angle	Degree
094	(02111)	Radar Incidence Angle	Degree
095	(02104)	Antenna Polarisation	Code Table
096	(21105)	Normalized Radar Cross Section	dB
097	(21106)	Kp Variance Coefficient (Alpha)	Numeric
098	(21107)	Kp Variance Coefficient (Beta)	Numeric
099	(21114)	Kp Variance Coefficient (Gamma)	dB

Number	Descriptor	Parameter	Unit
100	(21115)	Seawinds Sigma-0 Quality Flag	Flag Table
101	(21116)	Seawinds Sigma-0 Mode Flag	Flag Table
102	(08018)	Seawinds Land/Ice Surface Flag	Flag Table
103	(21117)	Sigma-0 Variance Quality Control	Numeric
104	(21113)	Number of Outer-Beam Sigma0 (aft of sat.)	Numeric
105	(05002)	Latitude (Coarse Accuracy)	Degree
106	(06002)	Longitude (Coarse Accuracy)	Degree
107	(21118)	Attenuation Correction On Sigma-0	dB
108	(02112)	Radar Look (Azimuth) Angle	Degree
109	(02111)	Radar Incidence Angle	Degree
110	(02104)	Antenna Polarisation	Code Table
111	(21105)	Normalized Radar Cross Section	dB
112	(21106)	Kp Variance Coefficient (Alpha)	Numeric
113	(21107)	Kp Variance Coefficient (Beta)	Numeric
114	(21114)	Kp Variance Coefficient (Gamma)	dB
115	(21115)	Seawinds Sigma-0 Quality Flag	Flag Table
116	(21116)	Seawinds Sigma-0 Mode Flag	Flag Table
117	(08018)	Seawinds Land/Ice Surface Flag	Flag Table
118	(21117)	Sigma-0 Variance Quality Control	Numeric

## 9. Appendix B: NetCDF data format

The wind products are also available in the NetCDF format, with the following characteristics:

- The data format meets the NetCDF Climate and Forecast Metadata Convention version 1.6 (<http://cf-pcmdi.llnl.gov/>).
- The data contain, contrary to the BUFR data, only level 2 wind and sea ice information, no sigma0 information. The aim was to create a compact and easy to handle product for oceanographic and climatological users.
- The data contain only the selected wind solutions, no ambiguity information.
- The wind directions are in oceanographic rather than meteorological convention (see section 4.1)
- The format is identical for OSCAT, ASCAT and any other scatterometer data.
- The data has file sizes somewhat smaller than those of the corresponding BUFR data (e.g., one half orbit file of 25 km wind data is 5 MB in BUFR and 1.8 MB in NetCDF). When compressed with gzip, the size of one file in NetCDF reduces to 0.6 MB.

The file name convention for the gzipped NetCDF product is

oscat\_YYYYMMDD\_HHMMSS\_scasa1\_ORBIT\_T\_SMPL\_VERS\_CONT\_I2.nc.gz where the meaning of the fields is identical to those in the BUFR file names (see section 4.2). The VERS part of the file name denotes the PenWP software version. A file name example is:

oscat\_20180403\_215814\_scasa1\_08043\_o\_250\_2105\_oww\_I2.nc.gz.

Below are some meta data contained in the NetCDF data files:

```
dimensions:
    NUMROWS = 790 ;
    NUMCELLS = 76 ;
variables:
    int time(NUMROWS, NUMCELLS) ;
        time:long_name = "time" ;
        time:units = "seconds since 1990-01-01 00:00:00" ;
    int lat(NUMROWS, NUMCELLS) ;
        lat:long_name = "latitude" ;
        lat:units = "degrees_north" ;
    int lon(NUMROWS, NUMCELLS) ;
        lon:long_name = "longitude" ;
        lon:units = "degrees_east" ;
    short wvc_index(NUMROWS, NUMCELLS) ;
        wvc_index:long_name = "cross track wind vector cell number" ;
        wvc_index:units = "1" ;
    short model_speed(NUMROWS, NUMCELLS) ;
        model_speed:long_name = "model wind speed at 10 m" ;
        model_speed:units = "m s-1" ;
    short model_dir(NUMROWS, NUMCELLS) ;
        model_dir:long_name = "model wind direction at 10 m" ;
        model_dir:units = "degree" ;
    short ice_prob(NUMROWS, NUMCELLS) ;
        ice_prob:long_name = "ice probability" ;
```

```

        ice_prob:units = "1" ;
short ice_age(NUMROWS, NUMCELLS) ;
        ice_age:long_name = "ice age (a-parameter)" ;
        ice_age:units = "dB" ;
int wvc_quality_flag(NUMROWS, NUMCELLS) ;
        wvc_quality_flag:long_name = "wind vector cell quality" ;
        wvc_quality_flag:flag_masks = 64, 128, 256, 512, 1024, 2048, 4096, 8192,
16384, 32768, 65536, 131072, 262144, 524288, 1048576, 2097152, 4194304 ;
        wvc_quality_flag:flag_meanings = "distance_to_gmf_too_large
data_are_redundant no_meteorological_background_used rain_detected rain_flag_not_usable
small_wind_less_than_or_equal_to_3_m_s large_wind_greater_than_30_m_s
wind_inversion_not_successful some_portion_of_wvc_is_over_ice
some_portion_of_wvc_is_over_land variational_quality_control_fails
knmi_quality_control_fails product_monitoring_event_flag product_monitoring_not_used
any_beam_noise_content_above_threshold poor_azimuth_diversity
not_enough_good_sigma0_for_wind_retrieval" ;
short wind_speed(NUMROWS, NUMCELLS) ;
        wind_speed:long_name = "wind speed at 10 m" ;
        wind_speed:units = "m s-1" ;
short wind_dir(NUMROWS, NUMCELLS) ;
        wind_dir:long_name = "wind direction at 10 m" ;
        wind_dir:units = "degree" ;
short bs_distance(NUMROWS, NUMCELLS) ;
        bs_distance:long_name = "backscatter distance" ;
        bs_distance:units = "1" ;

// global attributes:
        :title = "ScatSat-1 OSCAT Level 2 25.0 km Ocean Surface Wind Vector
Product" ;
        :title_short_name = "OSCAT-L2-25km" ;
        :Conventions = "CF-1.6" ;
        :institution = "EUMETSAT/OSI SAF/KNMI" ;
        :source = "ScatSat-1 OSCAT" ;
        :software_identification_level_1 = 2105 ;
        :instrument_calibration_version = 0 ;
        :software_identification_wind = 2105 ;
        :pixel_size_on_horizontal = "25.0 km" ;
        :service_type = "N/A" ;
        :processing_type = "0" ;
        :contents = "ovw" ;
        :granule_name = "oscat_20180403_215814_scasa1_08043_o_250_2105_ovw_l2.nc" ;
        :processing_level = "L2" ;
        :orbit_number = 8043 ;
        :start_date = "2018-04-03" ;
        :start_time = "21:58:14" ;
        :stop_date = "2018-04-03" ;
        :stop_time = "22:46:36" ;
        :equator_crossing_longitude = " 347.566" ;
        :equator_crossing_date = "2018-04-03" ;
        :equator_crossing_time = "21:35:38" ;
        :rev_orbit_period = "5962.0" ;
        :orbit_inclination = "98.1" ;
        :history = "N/A" ;
        :references = "ScatSat-1 Wind Product User Manual, http://www.osi-
saf.org/, http://www.knmi.nl/scatterometer/" ;

```



```

:comment = "Orbit period and inclination are constant values. All wind
directions in oceanographic convention (0 deg. flowing North)" ;
:creation_date = "2018-04-03" ;
:creation_time = "23:32:25" ;

```

The interpretation of the `wvc_quality_flag` integer value is as follows. The `flag_masks` correspond to certain flag bits that may or may not be set. This means that e.g. the 'flag\_mask' 64 corresponds to 'distance\_to\_gmf\_too\_large' and so on. The flag masks are powers of 2. The way to handle this is to take the integer value of the `wvc_quality_flag` and find out how it is composed of powers of 2. Suppose that one wants to test if the 'knmi\_quality\_control\_fails' flag bit is set. This is the 12th item in the flag list, corresponding to an integer value of 131072 ( $=2^{17}$ ) in the `flag_masks` table. You can test if this value is set using the function:

$(\text{integer flag value} / 2^{17}) \text{ modulo } 2$

which gives 1 if the 'knmi\_quality\_control\_fails' is set and 0 if the 'knmi\_quality\_control\_fails' is not set. The other flag bits can be tested in the same way. See the table below for the flag bits present in the `wvc_quality_flag`.

Description	Bit number
Not used	6
Not used	7
Not used	8
Rain flag algorithm detects rain	9
Not used	10
Reported wind speed is less than or equal to 3 m/s	11
Reported wind speed is greater than 30 m/s	12
Wind inversion not successful for wind vector cell	13
Some portion of wind vector cell is over ice	14
Some portion of wind vector cell is over land	15
Variational quality control data rejection	16
KNMI Quality Control (including rain) data rejection	17
Product monitoring flag	18
Product monitoring not used	19
Not used	20
Poor azimuth diversity among sigma-0 for wind retrieval	21
Not enough good sigma-0 available for wind retrieval	22